

Dynamic Threshold Schemes for Multi-Level Non-volatile Memories

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Joint work with:




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CoDESS Kickoff Meeting

Sept. 19th, 2013

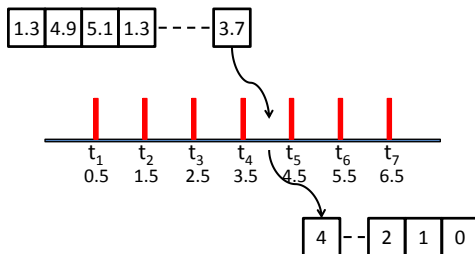
About me

- 1st year Ph.D. student in UCLA LORIS Lab
- Research areas: Coding for storage, combinatorics
- Selected Papers:
 -  F. Sala, R. Gabrys and L. Dolecek, "Dynamic threshold schemes for multi-level non-volatile memories," *IEEE Trans. on Commun.*, 2013.
 -  F. Sala and L. Dolecek, "Constrained Rank Modulation," in Proc. *IEEE Information Theory Workshop (ITW)*, 2013.
 -  F. Sala and L. Dolecek, "Counting Sequences Obtained from the Synchronization Channel," in Proc. *IEEE International Symposium on Information Theory (ISIT)*, 2013.

- 1 Introduction
 - Reading NVMs
 - Problems
 - Solutions
- 2 Dynamic Thresholding Analysis
 - Computing Dynamic Thresholds
 - Errors
 - Performance
 - Error-correction I
 - Error-correction II
- 3 Conclusion
 - Summary

Reading NVMs

- We wish to read a cell (in the MLC case) with q levels
- Traditionally, the voltage of a cell is measured, and this value is compared to a set of fixed thresholds
- For q levels, $q - 1$ thresholds are required
- **Ex:** $q = 4$, $\mathbf{t} = (0.5, 1.5, 2.5)$: $1.54 \rightarrow 2$, $2.9 \rightarrow 3$, $0.34 \rightarrow 0$

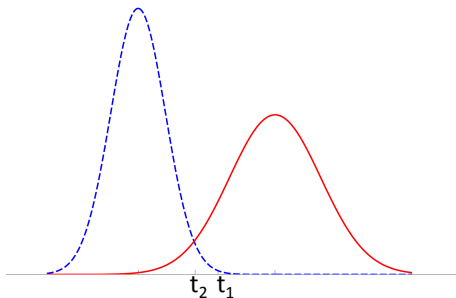


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- Distributions of cell voltages change over time. Fixed thresholds cannot react to these changes
- For example, charge leakage causes distributions to skew in one direction
- Overwriting can cause skew in the opposite direction



Existing Solutions

- Necessary to change thresholds over time: “dynamic thresholds” instead of fixed thresholds
- Existing industry solutions
- Ex: patents 7,876,621; 8,125,833 - Adaptive dynamic reading of flash memories / SanDisk:
 - Write known values, evenly distributed among $\{0, 1, \dots, q - 1\}$ to a subset of the cells in a block
 - Read the voltages of these cells and build a histogram
 - From the histogram, determine the statistical parameters and set thresholds accordingly

Our approach

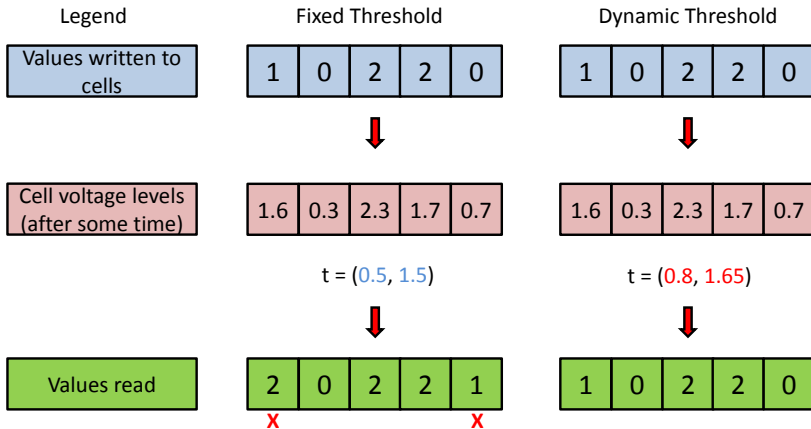
- We rely on a different dynamic thresholding approach.
- This solution was introduced (for the SLC case) by Zhou, Jiang, and Bruck in
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- Basic idea: pick the thresholds so that the number of cells at each level (in an entire block) stays the same

Example

Here, the blocksize $n = 5$ and the number of cell levels $q = 3$:



Comparison with existing approach

What are the advantages of this approach?

- Writing to cells is not (necessarily) needed, so write disturbs are minimized, yielding better device lifetime
- Circuits necessary for parameter estimation are not needed; complexity is reduced
- Interesting theoretical properties

Dynamic Thresholding Analysis

Computing Dynamic Thresholds

How can we generate the thresholds?

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- Decoder (i.e., cell reader) needs the # of cells at each level k_0, k_1, \dots, k_{q-1} . Two ways to accomplish this:
 - 1 Communicate these levels as metadata. $q - 1$ numbers \rightarrow cost $(q - 1) \lceil \log_q(n + 1) \rceil$

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 - 1 Communicate these levels as metadata. $q - 1$ numbers \rightarrow cost $(q - 1) \lceil \log_q(n + 1) \rceil$
 - 2 Fix the number of cells at each level in a block in advance: a constant-weight code. # of levels as close as possible: non-binary balanced code

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- Solution: Sort sequence in ascending order. Place thresholds between the positions indicated above
- Example: $\mathbf{k} = (1, 4, 2, 3)$. Place thresholds in sequence:

(0.4, | 0.8, 1.13, 1.2, 1.3, | 1.48, 2.12, | 2.14, 3.2, 3.8)

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 - Compare $\mathbf{k}(\mathbf{t}^{(0)})$ with the desired \mathbf{k} .
 - Appropriately adjust $\mathbf{t}^{(0)}$ to yield $\mathbf{t}^{(1)}$ and repeat

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- Increase $t^{(0)}$ to form $t^{(1)}$ and read with this new threshold
- If we have overshot, and there are now too many 0s, we may take

$$t^{(2)} = \frac{t^{(0)} + t^{(1)}}{2}$$

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- Every time we read a single cell is too frequent
- Instead, only generate dynamic thresholds at specific times, and use them as fixed thresholds until next “refresh”
- We can trigger a refresh:
 - After a fixed timeout
 - When an entire block of cells is being read
 - After sufficiently many cells have been written to

Error Analysis

When do errors occur when using D.T.?

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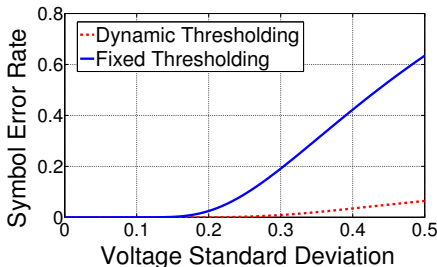
- By definition, *values* in a block cannot change
- But, the *order* of values may change
- Example: (2, 1, 3) is written. Voltages read are (2.4, 1.9, 1.8).
Then, (3, 2, 1) is the decoded word: a permutation of (2, 1, 3)

Error Analysis

- Note that a single error is not possible
- However, a large deviation in one voltage can cause 2 errors

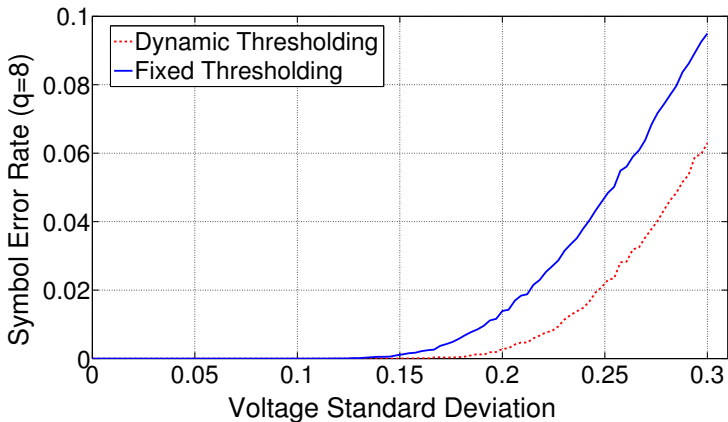
Error Analysis

- Note that a single error is not possible
- However, a large deviation in one voltage can cause 2 errors
- In general, errors take place when cells a, b with values $x < y$ have voltages such that $v_a > v_b$
- Fortunately, much more rare than fixed threshold errors:



Simulation Results

TLC cells ($q = 8$), $n = 10^5$, voltages modeled as Gaussians with increasing std. dev.



Theoretical Analysis

We have a specific scheme for selecting thresholds

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We have a specific scheme for selecting thresholds

- How does it compare to the “optimal” threshold?
 - Optimal threshold minimizes the number of errors N_e when reading a sequence
 - Cannot be determined without knowledge of the original sequence, so it is not “practical”
 - \mathbf{t}^* \rightarrow optimal threshold, \mathbf{t}^d \rightarrow dynamic threshold

Theoretical Analysis

- For this analysis, we set ℓ as the maximum deviation
 - Example: $\ell = 2$. $2 \rightarrow 4$ is a possible error. $2 \rightarrow 5$ is not
 - This limitation is reasonable: $2 \rightarrow 5$ error requires cell with value 2's voltage to exceed that of all cells with values 3,4
- "Performance bound:" How much worse do we do using \mathbf{t}^d instead of \mathbf{t}^* ?

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- "Performance bound:" How much worse do we do using \mathbf{t}^d instead of \mathbf{t}^* ?
- Result for $\ell \geq 1$:

$$N_e(\mathbf{t}^d) \leq (\ell + 1)N_e(\mathbf{t}^*)$$

- So: our scheme is very close to the theoretical (and unobtainable) optimal scheme

Error-correction codes

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- Need an ECC. Preferably one suited to the effects of D.T.
- Several strategies. Select between
 - 1 Using the “metadata” implementation
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and

- 1 Correcting a fixed number of errors (up to t errors limited to magnitude ℓ)
- 2 Correcting any number of errors (of magnitude limited to ℓ)

Error-correction codes

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Error-correction codes

- We refer to a code that corrects t errors limited to magnitude ℓ under D.T. as a (t, ℓ) -DTC code
- Start with the “metadata” approach, and assume that the decoder knows the number of cells at each level
- Received sequence \mathbf{y} is a permutation of the input \mathbf{x} with at least $n - t$ fixed points
- If $a \rightarrow b$ is an error, $|b - a| \leq \ell$

(t, ℓ) -DTC codes

Error vector $\mathbf{e} = \mathbf{y} - \mathbf{x}$ has certain interesting properties

- It is $(t - 1)$ -decomposable (using Roth's concept of "decomposability" for location-correction codes)

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- Difference of error vectors $\mathbf{e}_2 - \mathbf{e}_1$ is $2t - 2$ -decomposable
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- Thus, location-correction codes are suitable for use with D.T.

(t, ℓ) -DTC codes

- *Construction 1:* Let C be a $[n, n - 2]$ linear block code with parity-check matrix

$$H = \begin{bmatrix} a_1 & a_2 & \dots & a_n \\ a_1^2 & a_2^2 & \dots & a_n^2 \end{bmatrix},$$

where $S = \{a_1, a_2, \dots, a_n\}$ is a set in $\{0, 1, \dots, q - 1\}$

- Then, C is a $(2, q - 1)$ -DTC code if S is a Sidon set (all pairwise sums of elements are different: $a, b, c, d \in S \implies a + b \neq c + d$)

(t, ℓ) -DTC codes

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(t, ℓ) -DTC codes

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- Possible to derive constructions for any particular t, ℓ
- Particularly simple construction if $\ell = 1$
- Downside - code length limited by size of Sidon sets

Balanced (t, ℓ) -DTC codes

What about the “balanced code” D.T. implementation?

Balanced (t, ℓ) -DTC codes

What about the “balanced code” D.T. implementation?

- Say $n = eq$. Then, the space of possible codewords B is the set of permutations of the multiset

$$\underbrace{\{0, 0, \dots, 0\}}_{e \text{ 0s}}, \underbrace{\{1, 1, \dots, 1\}}_{e \text{ 1s}}, \dots, \underbrace{\{q-1, q-1, \dots, q-1\}}_{e (q-1)\text{s}}$$

- Code on permutations (“rank modulation codes”) can be generalized to codes on multi-set permutations to form balanced (t, ℓ) -DTC codes

ℓ -DTC codes

- We refer to a code that corrects any number of errors limited to magnitude ℓ under D.T. as a ℓ -DTC code
- *Construction 2:*

$$C = \{\mathbf{x} \in \text{GF}_q^n \mid 0 < x_i - x_j \leq \ell \implies i > j\}$$

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- Idea: Pick only one out of a candidate set of permutations
 - Select the permutation that is in “increasing” order
- Similar to ℓ -AEC (ℓ -asymmetric error correcting) codes studied by Bose and Elarief

ℓ -DTC codes

- Note: dual of the balanced (t, ℓ) -DTC code. In the balanced code approach, *all* codewords are permutations of one another. Here, *no* codewords are permutations

ℓ -DTC codes

- Note: dual of the balanced (t, ℓ) -DTC code. In the balanced code approach, *all* codewords are permutations of one another. Here, *no* codewords are permutations
- Duality due to the choice of channel: limited number of errors versus unlimited number of errors
- Decoding: Examine the received sequence \mathbf{y} for y_i and y_j with $i < j$ and $0 < y_i - y_j \leq \ell$. Then, flip y_i and y_j
- Continue until no further pairs are found

Summary

- We showed how to apply dynamic threshold schemes to multi-level cell memories
- We analyzed the performance of our scheme and showed it performs well practically while being close to the theoretical “optimal” limit
- We explored the question of combining error-correction codes and dynamic thresholding

Future work

- Develop practical error-correcting code constructions for multi-permutations

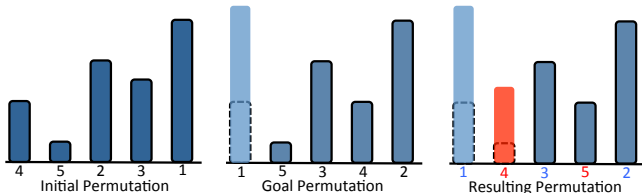
Thank you!

Constrained Permutations for Rank Modulation

- **Rank Modulation:** Represent information by cell rankings instead of absolute values. Ex:

$$\mathbf{x} = (2.3, 0.4, 1.2, 0.8, 2.0) \rightarrow (1 \ 5 \ 3 \ 4 \ 2)$$

- Resolves many NVM issues. Affected by **inter-cell coupling**: undesired rise in charge level due to large neighboring levels
- Solution: constrain differences between adjacent permutation elements. Constructions available. Asymptotically, capacity 1



Insertion and Deletion Sphere Bounds

- **Insertions** and **deletions** are particularly difficult types of errors:

BABCBDCC → AABBDCC

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- **Insertions** and **deletions** are particularly difficult types of errors:

BABCBDCC \rightarrow AABBDCC

- Useful to look at spheres formed by insertions and deletions
- Exact expression for # of sequences formed by **1 ins.**, **1 del**
 ($\tau(X)$ is the # of runs of identical consecutive symbols in X)

$$|E_{1,1}(X)| \approx \tau(X)(n(q-1) - 1) + 2$$

- Combinatorially-derived bounds available for larger number of **insertions** and **deletions**

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$$|E_{2,2}(X)| \geq \underbrace{\left(\sum_{i=0}^2 \binom{\tau(X)-2}{i} \right)}_{\geq |D_2(X)|} \underbrace{\left(n(q-1) + \binom{n}{2}(q-1)^2 \right)}_{|I_2(X')|}$$

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$$\begin{aligned}
 |E_{2,2}(X)| &\geq \underbrace{\left(\sum_{i=0}^2 \binom{\tau(X)-2}{i} \right)}_{\geq |D_2(X)|} \underbrace{\left(n(q-1) + \binom{n}{2} (q-1)^2 \right)}_{|b_2(X')|} \\
 &\quad - \left(\binom{\tau(X)-1}{3} + 3 \binom{\tau(X)-2}{2} \right) \\
 &\quad - \underbrace{\tau(X) \left(\binom{\tau(X)}{2} + \tau(X) - 1 \right) n(q-1) + 1}_{\geq - \sum_{x_1, x_2 \in D_2(X)} |b_2(x_1) \cap b_2(x_2)|}
 \end{aligned}$$